

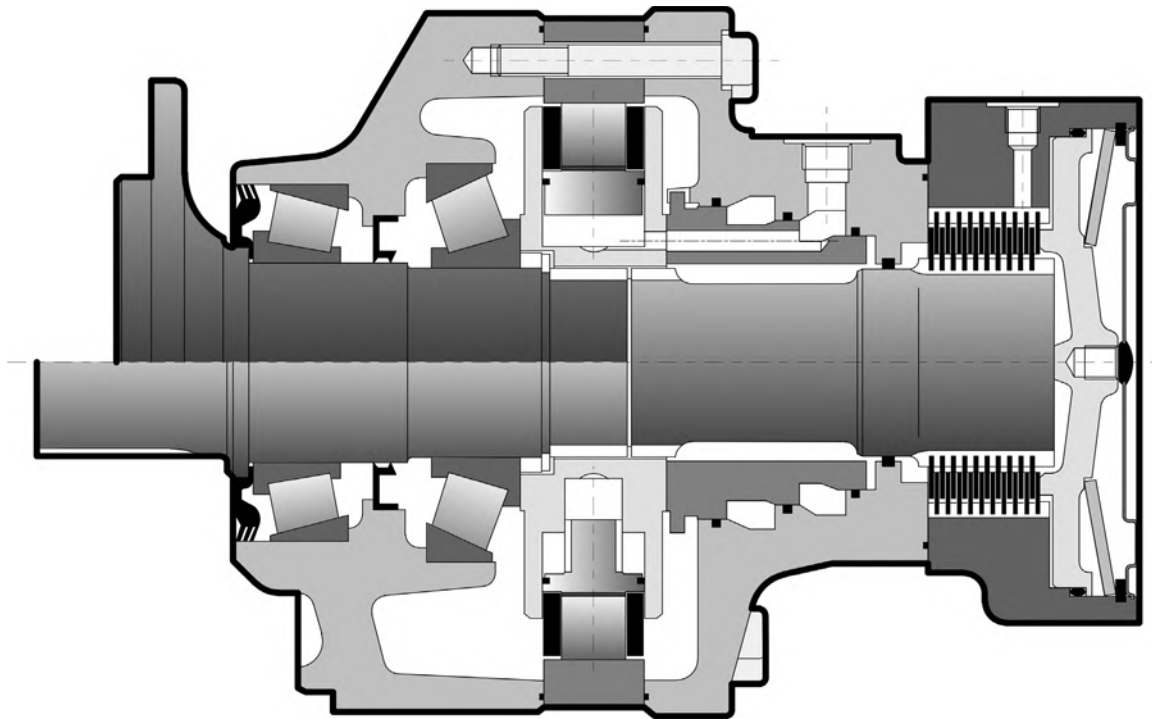
# MS25

## HYDRAULIC MOTORS

T E C H N I C A L C A T A L O G



# CHARACTERISTICS



Motor inertia 0.4 kg.m<sup>2</sup>

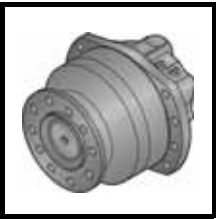
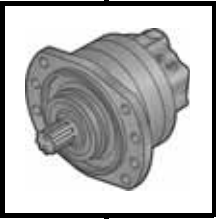

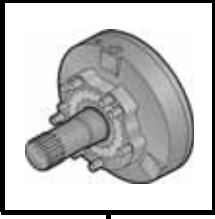
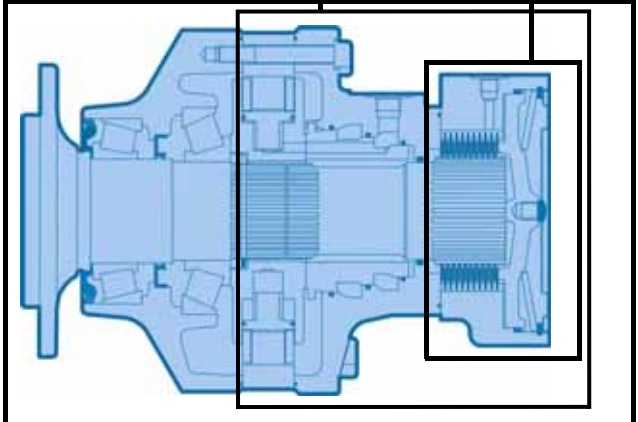
	C	Displacement		Theoretical torque		Max. power		Max. speed		Max. pressure
		1	2	1	1	2	2	1	2	
		cm <sup>3</sup> /tr [cu.in./rev.]	cm <sup>3</sup> /tr [cu.in./rev.]	at 100 bar Nm	at 1000 PSI [lb.ft]	kW [HP]	preferred kW [HP]	non-preferred kW [HP]	tr/min/RPM	bar [PSI]
Cams with equal lobes	8	2 004 [122,2]	1 002 [61,1]	3 186	[1 620]	90 [121]	60 [80]	45 [60]	145	145
	0	2 498 [152,4]	1 249 [76,2]	3 972	[2 020]				137	137
	1	2 752 [167,8]	1 376 [83,9]	4 376	[2 225]				125	135
	2	3 006 [183,3]	1 503 [91,7]	4 780	[2 431]				115	130
Cams with unequal lobes	A	2 505 [152,8]	1 503 [91,7]	3 983	[2 025]	90 [121]	60 [80]	45 [60]	115	130
			1 002 [61,1]							

❶ First displacement

❷ Second displacement

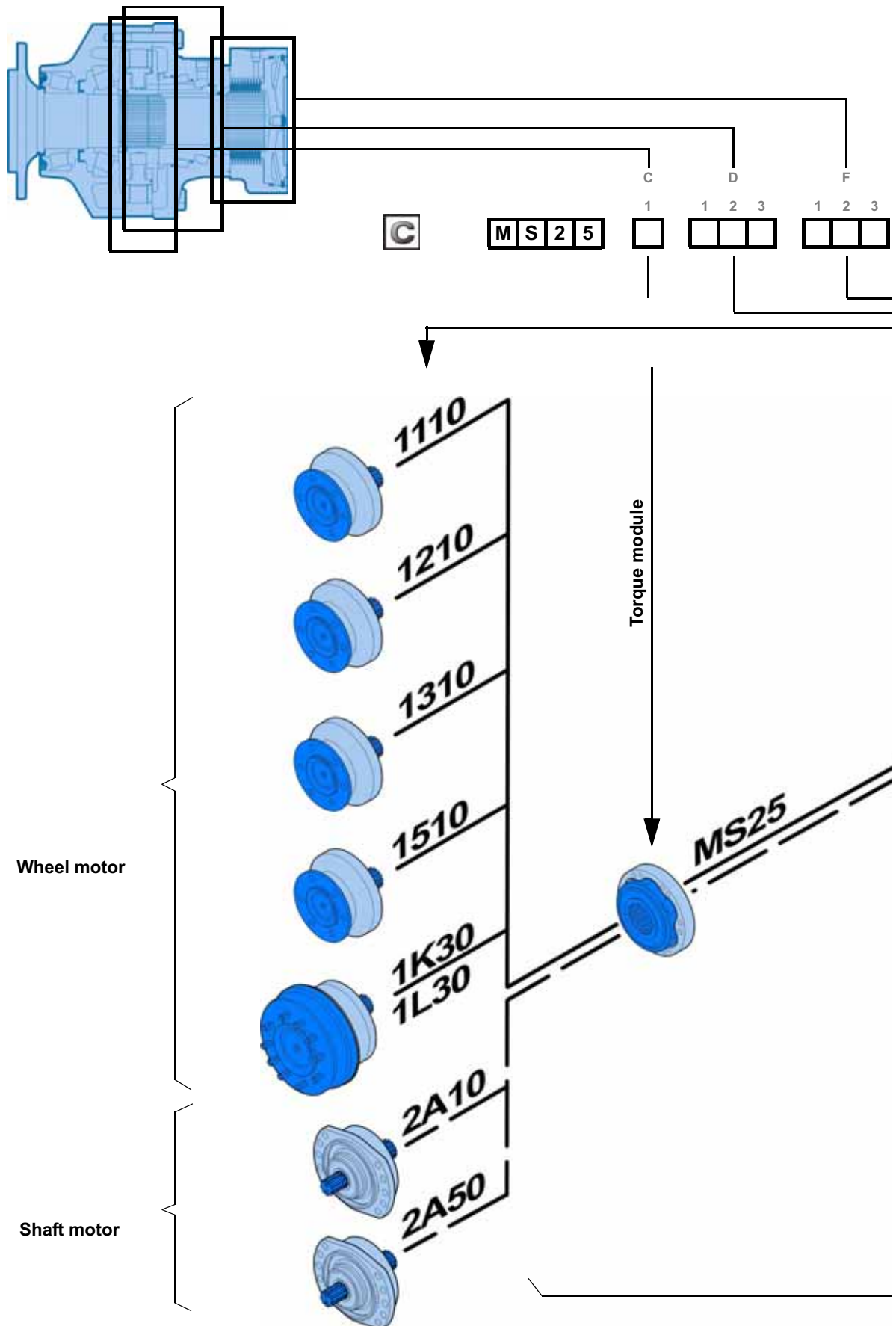


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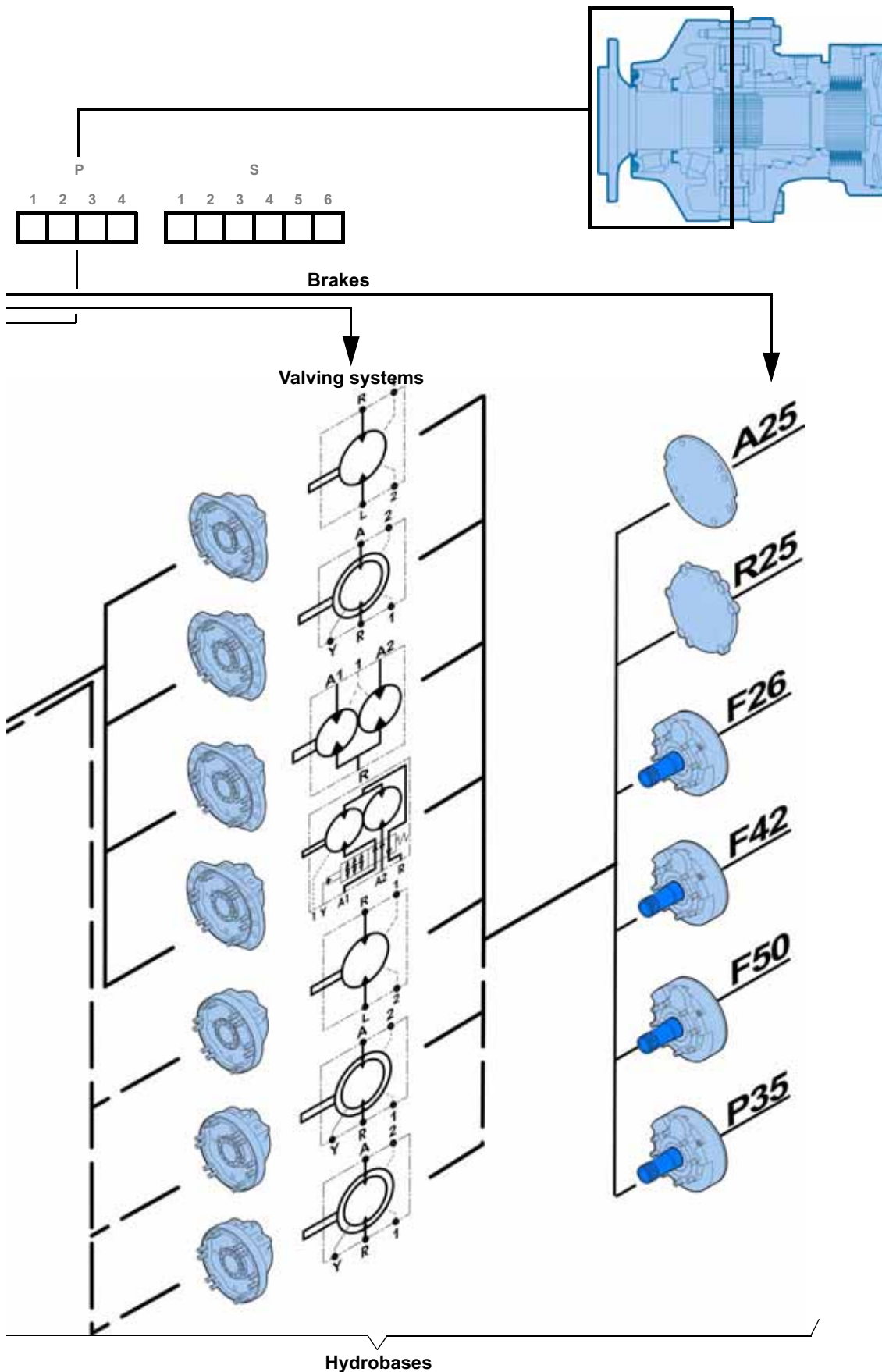


# MODUL



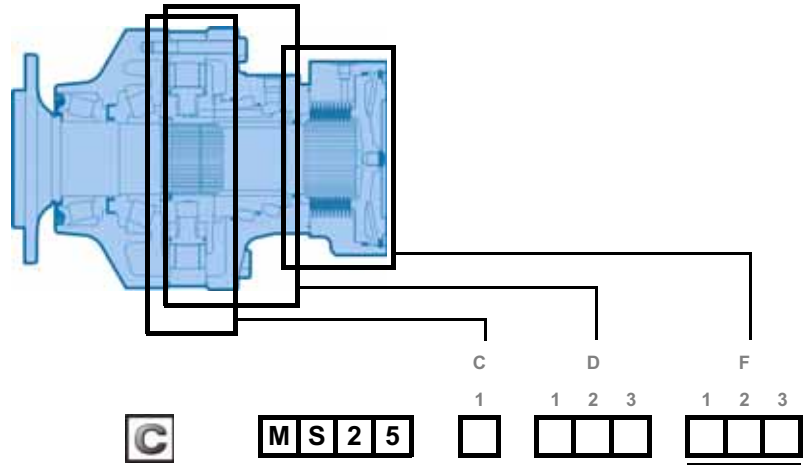


# ARITY





# MODEL



	①	②
	cm³/tr [cu.in/rev.]	cm³/tr [cu.in/rev.]
Cams with equal lobes	8 2 004 [122,2]	1 002 [61,1]
	0 2 498 [152,4]	1 249 [76,2]
	1 2 752 [167,8]	1 376 [83,9]
	2 3 006 [183,3]	1 503 [91,7]
Cams with unequal lobes	A 2 505 [152,8]	1 503 [91,7] 1 002 [61,1]

① First displacement  
② Second

Without mounting	1	1	-	-
Lug fixing	2	2	E	V
	1-displacement	2-displacement	Twin-Lock™	Twin-Lock™ or 2-displacement

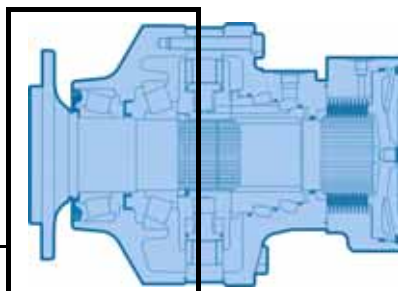
No transmission cover	0
ISO 6162 SAE flanges ISO 9974-1 metric connections	1

1-displacement valving	1
Symmetrical	A Ratio 2 B Ratio <2 C Ratio >2
2-displacement & Twin-Lock™ valving (Clockwise)	D Ratio 2 E Ratio <2 F Ratio >2
2-displacement & Twin-Lock™ valving (Counterclockwise)	G Ratio 2 H Ratio <2 J Ratio >2

Without brake (simple plate)	A 2 5 P 3 5 F 2 6 F 4 2 F 5 0 R 2 5
Brake	
Without brake (reinforced plate)	



# CODE



0	Without bearing support
1	Without mounting
2	Lug mounting

Without shaft	0
10 x Ø24 on Ø335	1
12 x Ø25 on Ø425	2
10 x Ø24 on Ø335	3
12 (8+4) Ø24 on Ø275	5
	H
	J
Drum brake (432 x 102)	K
	L
For male shaft bearing support	A

Without studs	1
With studs + nuts	2
With studs	3
M threaded holes	4

## Male shafts

NF E 22141 splines	1
DIN 5480 splines	5

Without cable	1	
Right-hand cable outlet	2	H - J
Left-hand cable outlet	3	
Without cable	4	
Right-hand cable outlet	5	K - L
Left-hand cable outlet	6	

Without Options or Adaptations	0
Fluorinated elastomer seals	1
T4 Speed sensor installed	2
Industrial bearing support	6
Diamond™	7
Predisposition for speed sensor	8
Double centering	9
Hollow shaft	A
Drain on the bearing support	B
Abrasive environment	C
Reinforced sealing	E
Special wheel rim mounting	G
Surface heat treatment of the shaft	J
TR Speed sensor installed	S

Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

Options



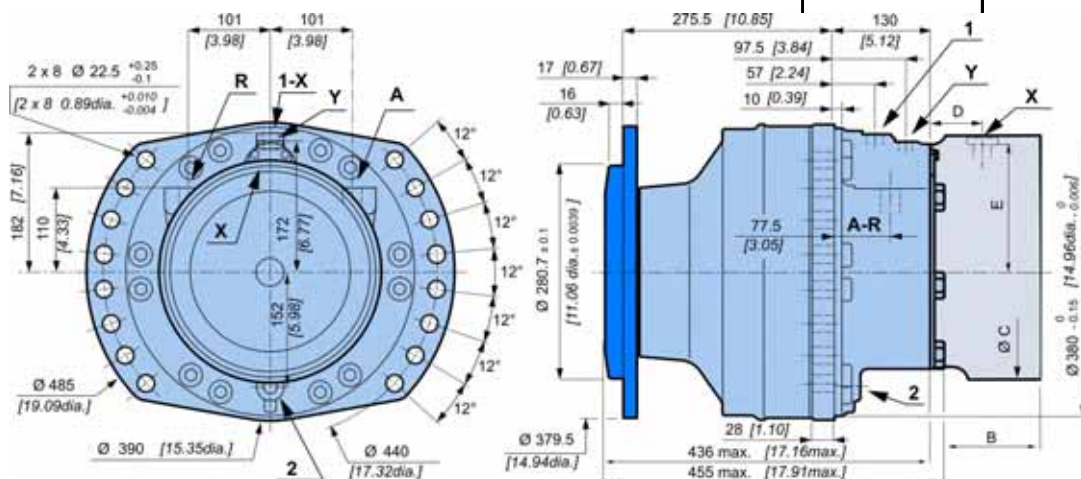






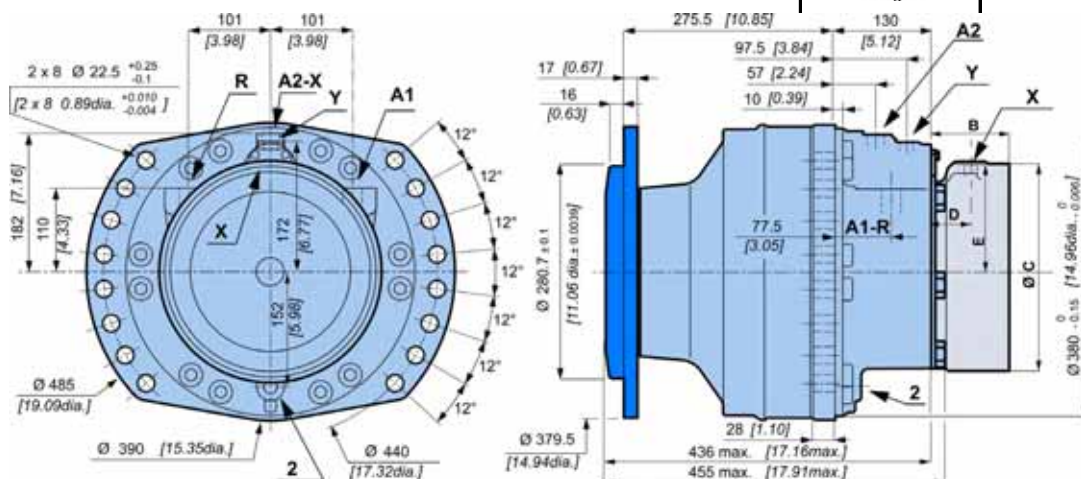
# WHEEL MOTOR

## Dimensions for standard (1110) 2-displacement motor



	210 kg [462 lb]	270 kg [594 lb]
	5,00 L [300 cu.in]	4,00 L [240 cu.in]

## Dimensions for standard (1210) Twin-Lock™



	210 kg [462 lb]	270 kg [594 lb]
	5,00 L [300 cu.in]	4,00 L [240 cu.in]



Also see 'Valving systems and hydrobases' section (thumbnail opposite).

	<b>C</b>	<b>P 3 5</b>	<b>F 2 6</b>	<b>F 4 2</b>	<b>F 5 0</b>
	B	85 [3.35]	128.5 [5.06]	142 [5.59]	152 [5.98]
	C	Ø280 [11.02 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]
	D	57 [2.24]	50 [1.95]	64.0 [2.52]	63.5 [2.50]
	E	138.5 [5.45]	183.5 [7.22]	183.5 [7.22]	183.5 [7.22]



Also see 'Brakes' section (thumbnail opposite).

Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

Options



## Support types

	C	D	F	P	S			
	1	1 2 3	1 2 3	1 2 3 4	1 2 3 4 5 6			
<div><div>M</div><div>S</div><div>2</div><div>5</div></div>	<div></div>	<div></div> <div></div> <div></div>	<div></div> <div></div> <div></div>	<div></div> <div></div> <div></div> <div></div>	<div></div> <div></div> <div></div> <div></div> <div></div> <div></div>			
<div>C</div>	A mm [in]	B mm [in]	C mm [in]	D mm [in]	E mm [in]	N mm [in]	Wheel rim mountings	L mm [in]
<div><div>1</div><div>1</div><div>1</div><div>0</div></div> <div>P</div>	Ø 280,7 [11,05 dia.]	Ø 335 [13,19 dia.]	Ø 379 [14,92 dia.]	275,5 [10,85]	Ø 390 [15,35 dia.]	Ø 24 [0,94 dia.]	10 x M22x1.5	17 [0,67]
<div><div>1</div><div>2</div><div>1</div><div>0</div></div> <div>P</div>	Ø 370 [14,57 dia.]	Ø 425 [16,73 dia.]	Ø 472 [18,58 dia.]	333,45 [13,13]	Ø 390 [15,35 dia.]	Ø 26 [1,02 dia.]	12 x M24x2	24 [0,94]
<div><div>1</div><div>3</div><div>1</div><div>0</div></div> <div>P</div>	Ø 280,7 [11,05 dia.]	Ø 335 [13,19 dia.]	Ø 385 [15,16 dia.]	236,5 [9,31]	Ø 390 [15,35 dia.]	Ø 24 [0,94 dia.]	10 x M22x1.5	17 [0,67]
<div><div>1</div><div>5</div><div>1</div><div>0</div></div> <div>P</div>	Ø 220,7 [8,69 dia.]	Ø 275 [10,83 dia.]	Ø 314 [12,36 dia.]	241,5 [9,51]	Ø 390 [15,35 dia.]	8 x Ø 22 [8 x 0,87 dia.] 4 x Ø 22 [4 x 0,87 dia.]	-	17 [0,67]
<div><div>1</div><div>K</div><div>3</div><div>0</div><div>1</div><div>L</div><div>3</div><div>0</div></div> <div>P</div>	Ø 280,7 [11,05 dia.]	Ø 335 [13,19 dia.]	Ø 461,5 [18,17 dia.]	337,95 [13,31]	<div><div><div>74 [2,91]</div><div>40 [1,57]</div><div>30°</div><div>M10x1,5</div></div></div>		10 x M22x1.5	45 [1,77]
<div><div></div><div></div></div>	<div>Also see 'Brakes' section (thumbnail opposite).</div>					<div></div>		



Also see 'Brakes' section  
(thumbnail opposite).

## Studs

		P mm [in]	C min. mm [in]	C max. mm [in]	D mm [in]		Class	(1) * N.m [lb.ft]	(2) * N.m [lb.ft]
Various studs	M22 x 1.5	80 [3.15]	5 [0.20]	36 [1.42]	26 [1.02]		12.9	695 [512.6]	1 050 [774.4]
	M24 x 2	95 [3.74]		38 [1.50]	30 [1.18]			910 [671.2]	1 150 [848.2]
Screws	M20	-	-	-	-		12.9	600 [442.5]	770 [567.9]

(\*) The tightening torques are given for the indicated loads.

(1) **Wheel rim** : Suggested tightening torque for wheel rim mountings (Re steel disc > 240 N/mm<sup>2</sup> [>34 800 PSI]).

(2) **Standard** : Suggested tightening torque in other cases (Re steel flange 360 > N/mm<sup>2</sup> [>52 215 PSI])



See generic installation motors N°801478197L.



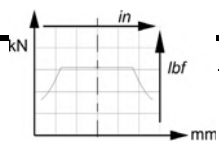
## Load curves

### Permissible radial loads

Test conditions :

**Static** : 0 tr/min [0 RPM] 0 bar [0 PSI]

**Dynamic** : 0 tr/min [0 RPM], code 0 displacement, without axial load at max. torque



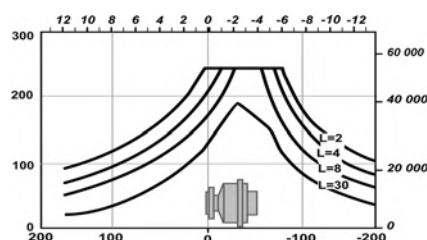
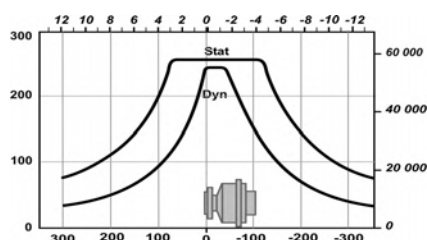
### Service life of bearings

Test conditions :

**L** : Millions B10 revolutions at 150 bars (average pressure), with 25 cSt fluid, code 0 displacement, without axial load.

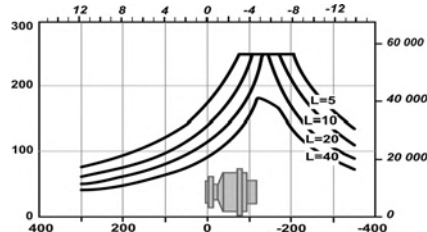
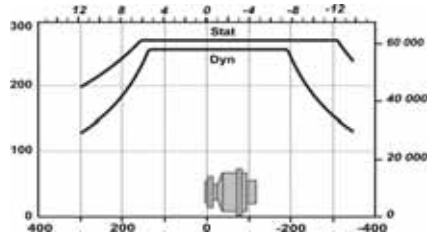
1 1 1 0  
1 2 3 4

P



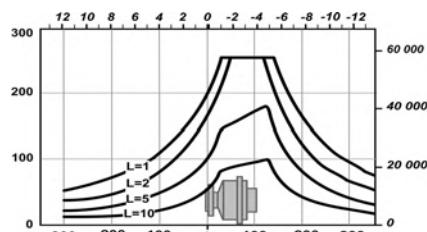
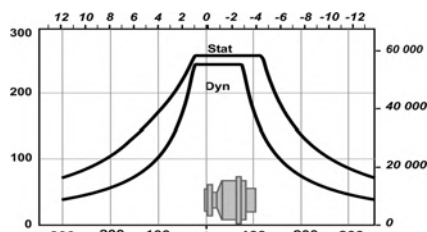
1 2 1 0  
1 2 3 4

P



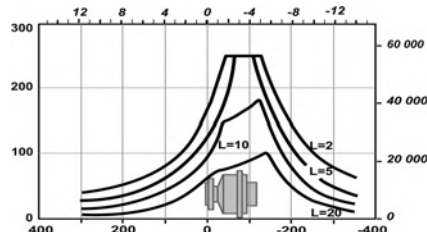
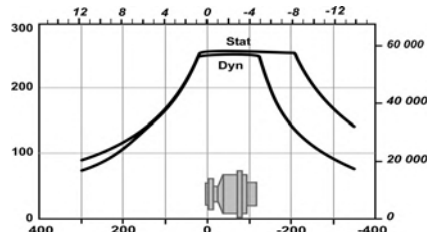
1 3 1 0  
1 2 3 4

P



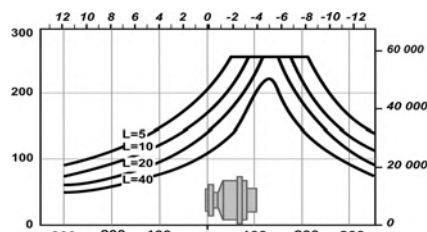
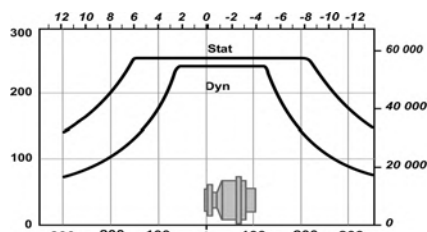
1 5 1 0  
1 2 3 4

P



1 K 3 0  
1 L 3 0  
1 2 3 4

P



The service life of the components is influenced by the pressure. You must check that the combination of forces applied (Axial load / Radial load) is compatible with the permissible loads for the components, and that the resulting service lives of these components complies with the application's specifications. For an accurate calculation, consult your Poclain Hydraulics application engineer.



Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake





Options

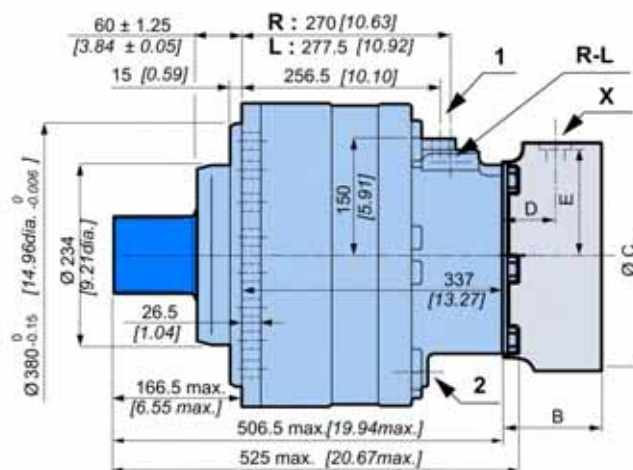
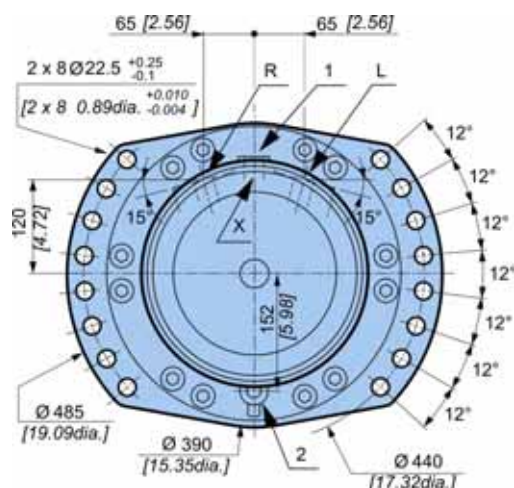








# SHAFT MOTOR

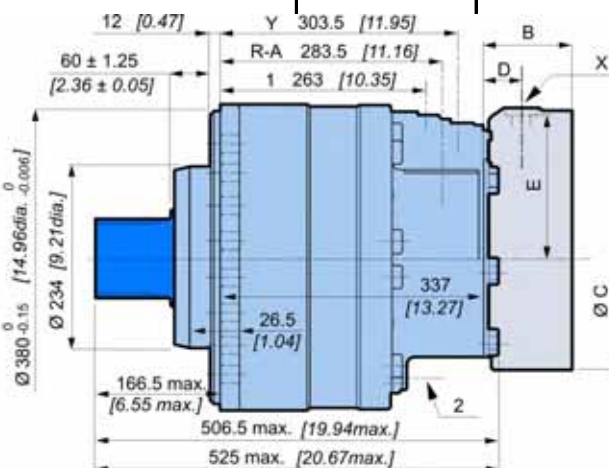
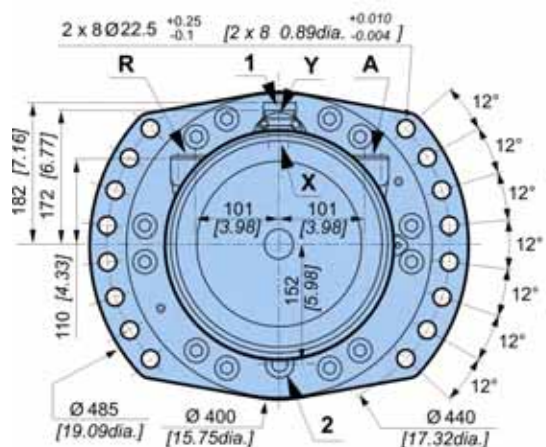
### Dimensions for standard (2A50) 1-displacement motor

	195 kg [429 lb]	255 kg [561 lb]
	5,00 L [300 cu.in]	4,00 L [240 cu.in]
		

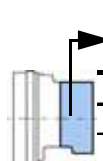


### Dimensions for standard (2A50) 2-displacement motor

	195 kg [429 lb]	255 kg [561 lb]
	5,00 L [300 cu.in]	4,00 L [240 cu.in]
		



**Also see 'Valving systems and hydrobases' section (thumbnail opposite).**

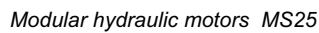


	<b>C</b>	<b>P 3 5</b>	<b>F 2 6</b>	<b>F 4 2</b>	<b>F 5 0</b>
<b>B</b>	85 [3.35]	128.5 [5.06]	142 [5.59]	152 [5.98]	
<b>C</b>	Ø280 [11.02 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	
<b>D</b>	57 [2.24]	50 [1.95]	64.0 [2.52]	63.5 [2.50]	
<b>E</b>	138.5 [5.45]	183.5 [7.22]	183.5 [7.22]	183.5 [7.22]	



**Also see 'Brakes' section**  
(thumbnail opposite).





C                      D                      F                      P                      S  
 1                      1 2 3                      1 2 3                      1 2 3 4                      1 2 3 4 5 6



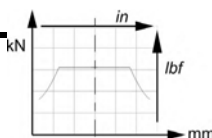
## Load curves

### Permissible radial loads

Test conditions :

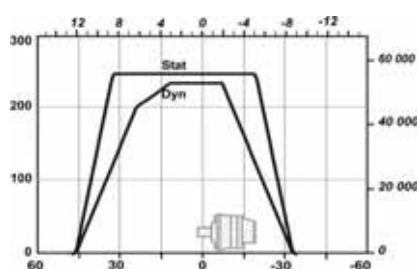
**Static** : 0 tr/min [0 RPM] 0 bar [0 PSI]

**Dynamic** : 0 tr/min [0 RPM], code 0 displacement, without axial load at max. torque



2	A	5	0
2	A	1	0

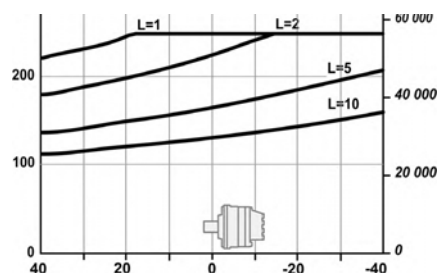
P



### Service life of bearings

Test conditions :

L : Millions B10 revolutions at 150 bars (average pressure), with 25 cSt fluid, code 0 displacement, without axial load.



The service life of the components is influenced by the pressure. You must check that the combination of forces applied (Axial load / Radial load) is compatible with the permissible loads for the components, and that the resulting service lives of these components complies with the application's specifications. For an accurate calculation, consult your Poclain Hydraulics application engineer.

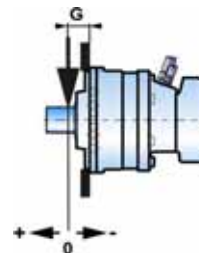


G

2	A	1	0
2	A	5	0

115,75 [4,56]

125 [4,92]



Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

Options





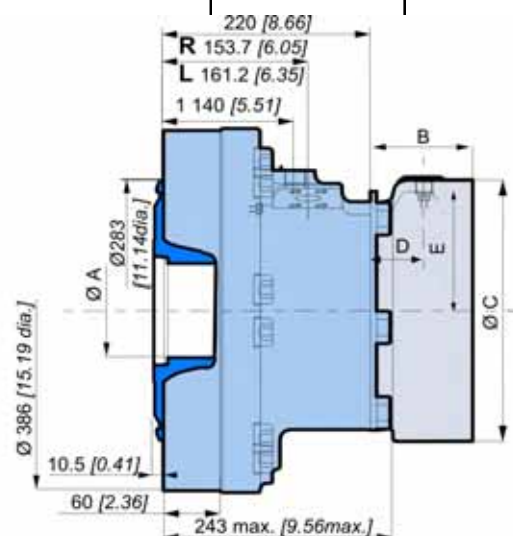
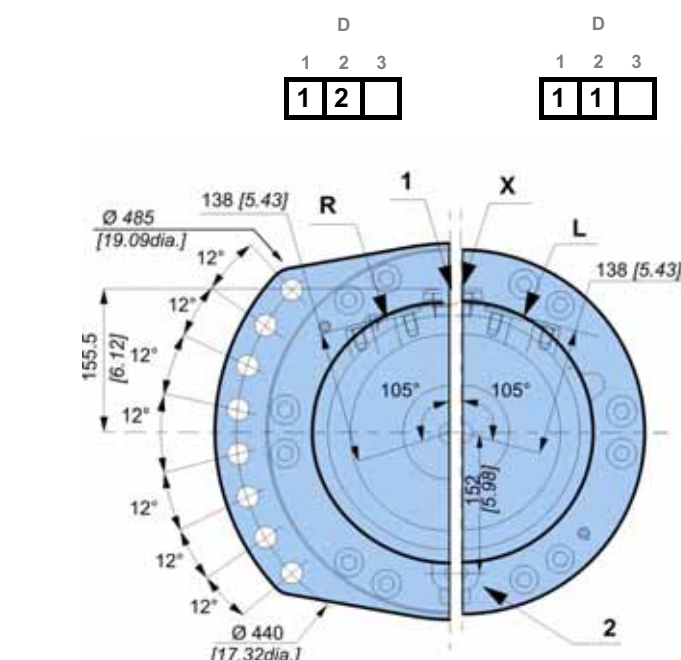


# VALVING SYSTEMS AND HYDROBASES

				C	D			F			P				S					
				1	1	2	3	1	2	3	1	2	3	4	1	2	3	4	5	6
M	S	2	5																	

## Dimensions for 1-displacement valving

	13,8 kg [30 lb]	19,9 kg [44 lb]
	0,35 L [21 cu.in]	0,45 L [27 cu.in]



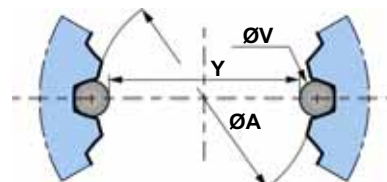
	C	P 3 5	F 2 6	F 4 2	F 5 0
B	85 [3.35]	128.5 [5.06]	142 [5.59]	152 [5.98]	
C	Ø280 [11.02 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	
D	57 [2.24]	50 [1.95]	64.0 [2.52]	63.5 [2.50]	
E	138.5 [5.45]	183.5 [7.22]	183.5 [7.22]	183.5 [7.22]	

Also see 'Brakes' section (thumbnail opposite).

## Cylinder block splines

(as per standard NF E22-141)

ØA	Module	Z	Dimension on 2 pins	
			Y	ØV
100 [3,937]	2,5	38	90,169 [3,550]	5 [0,197]



You are advised to have the installation validated by your Poclain Hydraulics application engineer before using the hydraulic unit in an application.



We must provide you with a detailed plan of the interface for any hydraulic unit use, consult your Poclain Hydraulics sales engineer.

Modularity and Model code

Wheel motor

Shaft motor

Valving systems and hydrobases

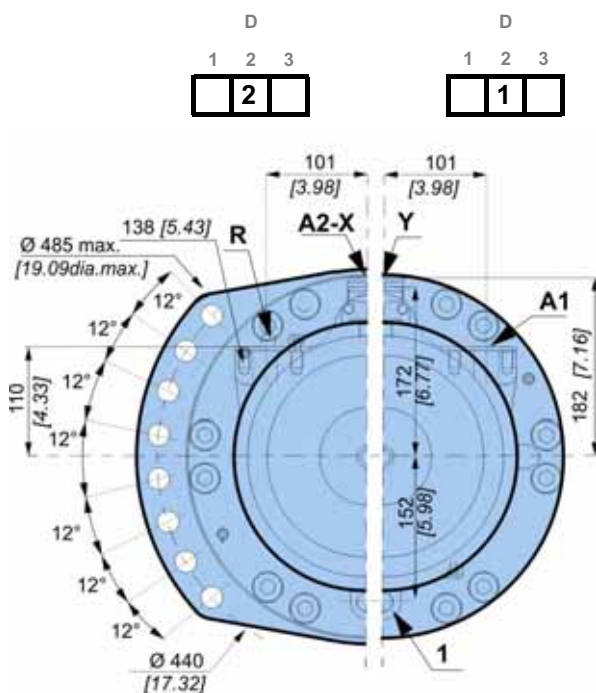
Brake

Options

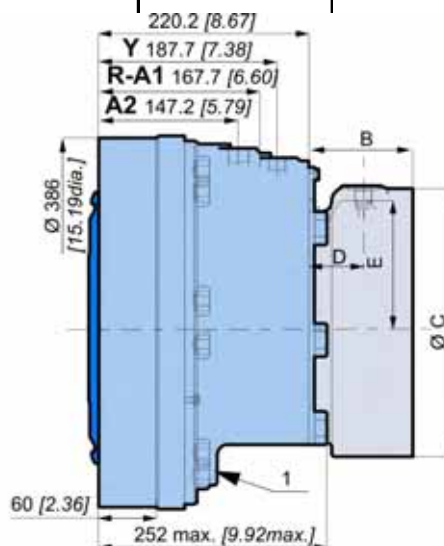




## Dimensions for Twin-Lock™



	13,8 kg [30 lb]	19,9 kg [44 lb]
	0,35 L [21 cu.in]	0,45 L [27 cu.in]



	<b>C</b>	<b>P 3 5</b>	<b>F 2 6</b>	<b>F 4 2</b>	<b>F 5 0</b>
<b>B</b>	85 [3.35]	128.5 [5.06]	142 [5.59]	152 [5.98]	
<b>C</b>	Ø280 [11.02 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	Ø375 [14.76 dia.]	
<b>D</b>	57 [2.24]	50 [1.95]	64.0 [2.52]	63.5 [2.50]	
<b>E</b>	138.5 [5.45]	183.5 [7.22]	183.5 [7.22]	183.5 [7.22]	



Also see 'Brakes' section  
(thumbnail opposite).

Modularity and  
Model code

Wheel motor

Shaft motor

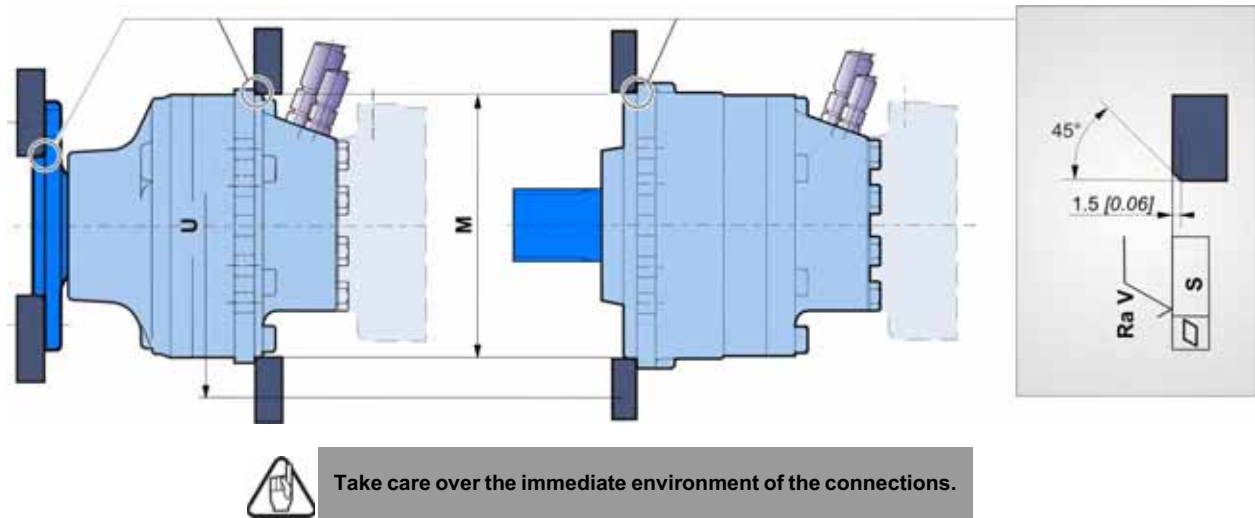
Valving systems  
and hydrobases



Brake

Options



## Chassis mountings



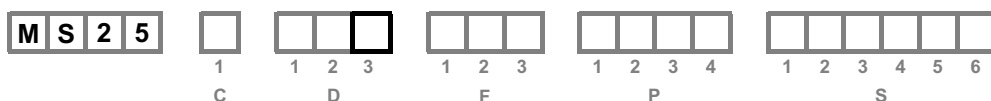
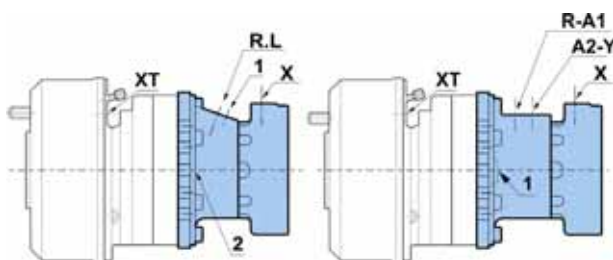
	$\varnothing M$ <sup>(1)</sup>	$\varnothing U$	S	Ra V		Class	 *
Wheel motor	380	440	0,2	12,5µm	2 x 8 Ø22.5	8,8	410 N.m
Shaft motor	[14,96]	[17,32]	[0,008]	[0,49µin]	M20 x 2		[302 lb.ft]
<sup>(1)</sup> +0,3 [+0,012] +0,2 [+0,008]							

\* : Min. values for torque and load to be transmitted.



## Hydraulic connections

connections



		Old standards	Standards	Power supply	Case drain	2 <sup>nd</sup> displacement control	Control of parking break	Control of drum break
				R-L	1, 2		X	XT
	1	ISO 6 162 DIN 3 852	ISO 6 162 ISO 9 974-1	DN25 PN400	M22x1.5		M18x1.5	
				R-A	1, 2	Y	X	
	1	ISO 6 162 DIN 3 852	ISO 6 162 ISO 9 974-1	DN25 PN400	M22x1.5	M18x1.5	M18x1.5	
	1*	ISO 6 162 DIN 3 852	ISO 6 162 ISO 9 974-1	DN25 PN400	M27x2	M20x1.5	M18x1.5	
				R-A1	A2	1, 2	Y	X
	1	ISO 6 162 DIN 3 852	ISO 6 162 ISO 9 974-1	DN25 PN400	M27x2	M22x1.5	M18x1.5	M18x1.5
			ISO 9 974-1					M14x1.5
Max. pressures		MS	bar [PSI]	450 [6 527]	1 [15]	30 [435]	30 [435]	120 [1 740]

\* : Only symmetrical valving



You are strongly advised to use the fluids specified in brochure "Installation guide" N° 801478197L.



To find the connections' tightening torques, see the brochure "Installation guide" N° 801478197L.

Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

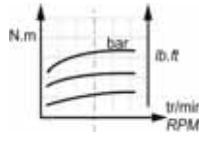
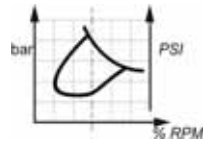
Options



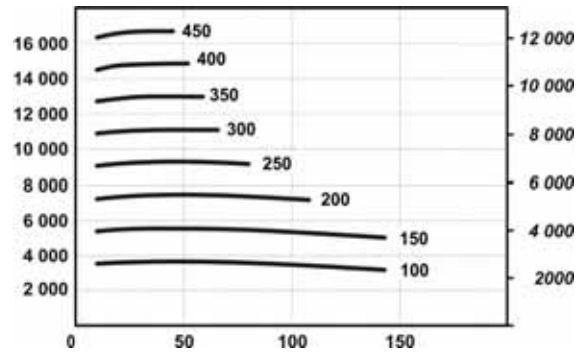
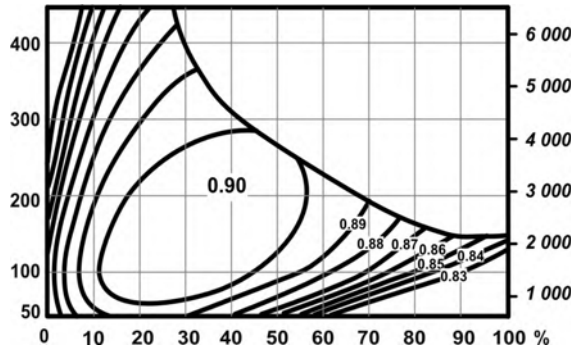
## Efficiency

### Overall efficiency

Average values given for guidance for code 0 displacement after 100 hours of operation with HV46 hydraulic fluid at 50°C [122°F].



### Actual output torque



The starting torque is taken to be approximately 85% of the first value for available pressure. For a precise calculation, consult your Poclain Hydraulics application engineer.

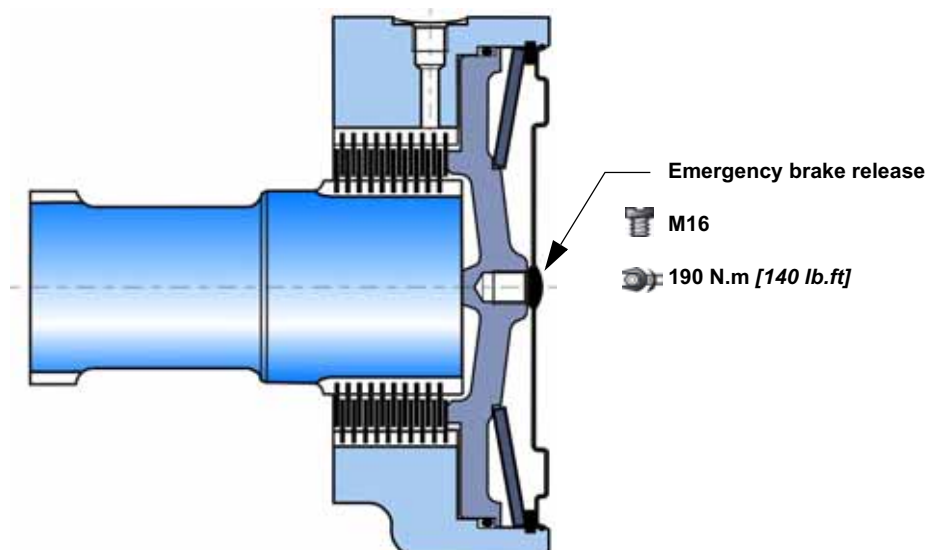




# BRAKES

## Rear brake

				C	D			F			P				S					
				1	1	2	3	1	2	3	1	2	3	4	1	2	3	4	5	6
M	S	2	5					P	3	5										



### Brake principle

This is a multidisc brake which is activated by a lack of pressure. The spring exerts a force on the piston, which presses on the fixed and mobile discs, and immobilizes the shaft. The braking torque decreases in linear proportion to the brake release pressure.


**P 3 5**

Parking brake torque at 0 bars on housing (new brake)	20 500 Nm [15 120 lb.ft]
Dynamic emergency braking torque at 0 bars on housing (max. 10 uses of emergency brakes)	13 325 Nm [9 830 lb.ft]
Residual parking braking at 0 bars on housing *	15 375 Nm [11 340 lb.ft]
Min. brake release pressure	12 bar [174 PSI]
Max. brake release pressure	30 bar [435 PSI]
Oil capacity	700 cm³ [42,7 cu.in]
Volume for brake release	70 cm³ [4,3 cu.in]

\* After emergency brake has been used



Do not run in multidisc brakes.



A functional check of the parking brake must be carried out each time it is used as an auxiliary brake (or emergency brake). For all vehicles capable of speeds over 25 km/hour, please contact your Poclain Hydraulics application engineer.

Modularity and  
Model code

Wheel motor

Shaft motor

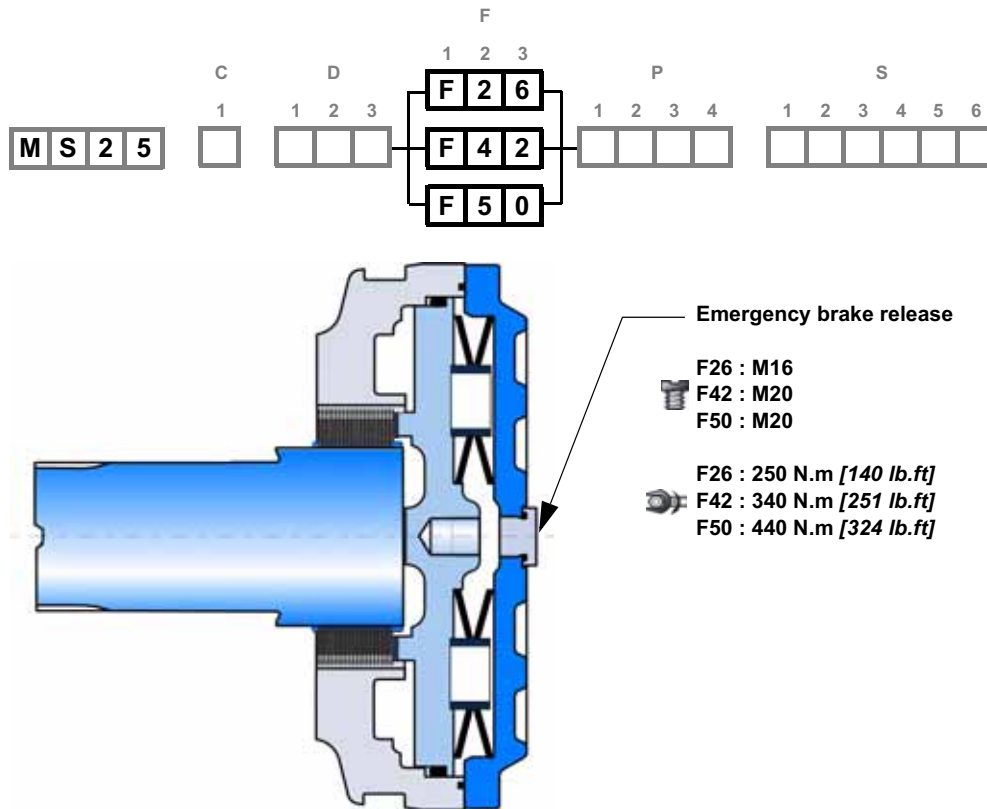
Valving systems  
and hydrobases

Brake

Options



## Rear brake



## Brake principle

This is a multidisc brake which is activated by a lack of pressure. The spring exerts a force on the piston, which presses on the fixed and mobile discs, and immobilizes the shaft. The braking torque decreases in linear proportion to the brake release pressure.

	F 2 6	F 4 2	F 5 0
Parking brake torque at 0 bars on housing (new brake)	26 730 Nm [19 720 lb.ft]	25 000 Nm [18 440 lb.ft]	30 000 Nm [22 130 lb.ft]
Dynamic emergency braking torque at 0 bars on housing	17 375 Nm [12 820 lb.ft]	16 250 Nm [11 990 lb.ft]	19 500 Nm [14 380 lb.ft]
Residual parking braking at 0 bars on housing *	20 048 Nm [14 790 lb.ft]	18 750 Nm [13 830 lb.ft]	22 500 Nm [16 600 lb.ft]
Min. brake release pressure	10 bar [138 PSI]	12 bar [174 PSI]	12 bar [174 PSI]
Max. brake release pressure	30 bar [435 PSI]	30 bar [435 PSI]	30 bar [435 PSI]
Oil capacity	200 cm <sup>3</sup> [12,2 cu.in]	400 cm <sup>3</sup> [24,4 cu.in]	450 cm <sup>3</sup> [27,5 cu.in]
Volume for brake release	120 cm <sup>3</sup> [7,3 cu.in]	135 cm <sup>3</sup> [8,2 cu.in]	135 cm <sup>3</sup> [8,2 cu.in]

\* After emergency brake has been used



Do not run in multidisc brakes.



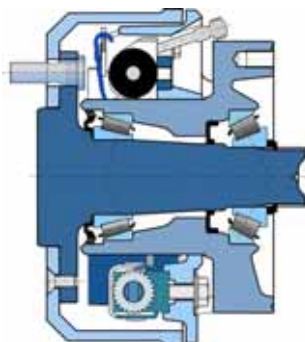
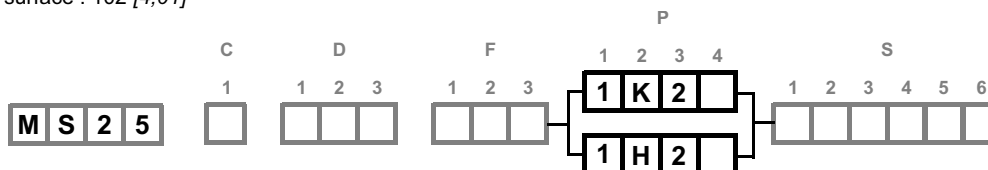
A functional check of the parking brake must be carried out each time it is used as an auxiliary brake (or emergency brake). For all vehicles capable of speeds over 25 km/hour, please contact your Poclain Hydraulics application engineer.



## Drum brake (432 x 102)

Diameter of brake pads : Ø 432 [17 dia.]

Width of friction surface : 102 [4,01]



### Brake pads

Asbestos free material	BERAL 1109 or JURID 505
Compensation for wear	Automatic

### Hydraulically controlled dynamic braking

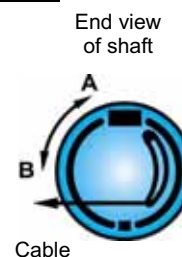
Max. permissible continuous brake torque	16 200 N.m [11 948 lb.ft]
Pressure to obtain max. permissible continuous brake torque	71 bar [1 028 PSI]
Max. permissible brake torque	27 000 N.m [19 914 lb.ft]
Pressure to obtain max. permissible brake torque	120 bar [1 740 PSI]

### Fluid

Mineral	Yes	H - K
DOT 3 / DOT 4 / SAE J1703	No	
Max. volume required to bring pads into contact	10.2 cm <sup>3</sup> [0.62 cu.in]	

### Mechanically controlled parking brake

Max. braking torque		27 000 N.m [19 914 lb.ft]
Max permissible force on the cable		5 700 N [1 281 lbf]
Force required to bring pads into contact		37 N [8 lbf]
Stroke required to bring pads into contact (new brake)	A	19 mm [0.73 "]
	B	16 mm [0.63 "]



The max. braking torque can only be obtained when the brake has been run in. Consult your Poclain Hydraulics application engineer.

### Control

The drum brakes can be controlled hydraulically (service brake) and by a cable (mechanical control for parking brake).



Do not use hydraulic and mechanical brake controls simultaneously.



See also 'Wheel motor' section (thumbnail opposite)



When making an encoding request, you must indicate the following information:

- The material of the brake linings,
- The type of connection at the end of the parking brake control cable,
- Fill out the technical questionnaire for validation of the brake.

Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

Options





# OPTIONS

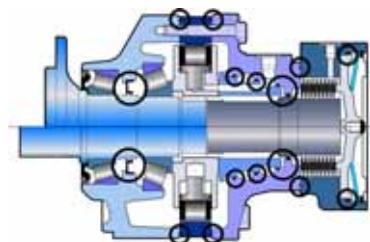
				C	D			F			P				S					
				1	1	2	3	1	2	3	1	2	3	4	1	2	3	4	5	6
M	S	2	5	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	



You can accumulate more than one optional part. Consult your Poclain Hydraulics sales engineer.

## 1 - Fluorinated elastomer seals

Nitrile seals marked in the figure below replaced by fluorinated elastomer seals.



Consult your Poclain Hydraulics sales engineer.

## 2 - S - 8 - Installed speed sensor or predisposition

### Designation

T4 Speed sensor installed



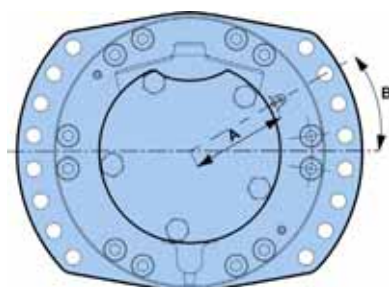
2

TR Speed sensor installed (direction of rotation)

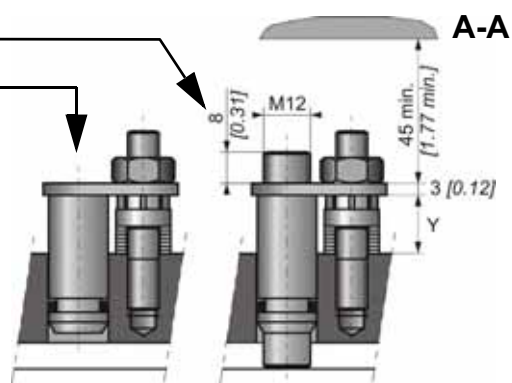
S

Predisposition for speed sensor

8



	mm [in]	mm [in]
A	118,9 [4,68]	118,9 [4,68]
B	0°	20°
	2-displacement	1-displacement



Max. length Y= 15.6

Standard number of pulses per revolution= 56



Look at the "Mobile Electronic" N° A01889D technical catalogue for the sensor specifications and its connection.



To install the sensor, see the "Installation guide" brochure No. 801478197L.

Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

Options



## 6 - Industrial support

Reduction of around 50% from the rated value in the bearings' preload value.



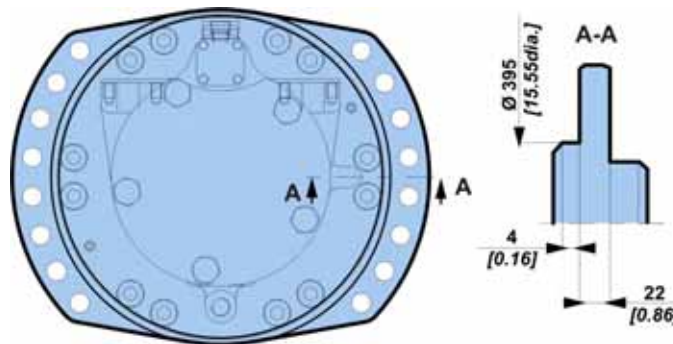
For a precise calculation, consult your Poclain Hydraulics application engineer.

## 7 - Diamond™

Special treatment of the motor core which considerably increases its strength, making the motor much more tolerant to temporary instances of the operating conditions being exceeded.

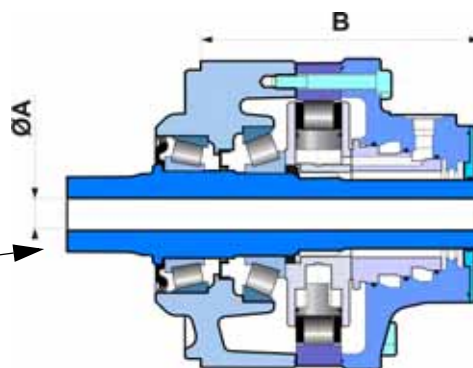
## 9 - Double-centering valving cover

This option allows a motor to be installed from the front or the back.



## A - Hollow shaft

2 M8 screws: Ø 80mm [3.14"dia.]  
diametrically opposite.  
Threaded depth  
12 mm min. [0.47"min.]

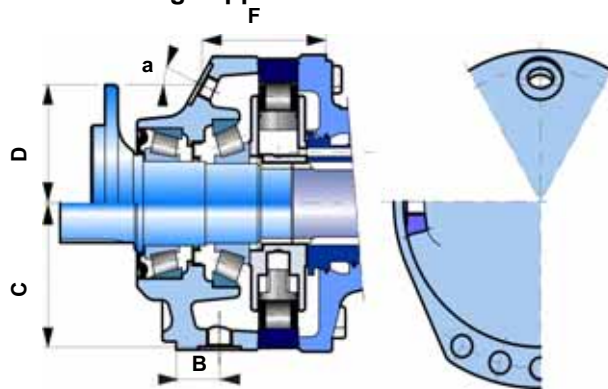


A mm [in]	B mm [in]
Ø 60 [2,36 dia.]	352,5 [13,88]

Radial load x 0.75  
No torque transmittable to the rear



## B - Drain on the bearing support

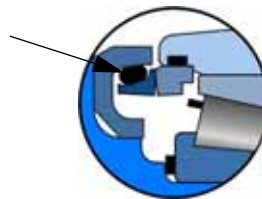


		B	C	D	F	a
		mm [in]	mm [in]	mm [in]	mm [in]	
Shaft motor	M22 x 1.5	56,0 [2,20]	193 [7,60]	112,0 [4,41]	113 [4,43]	30°
Wheel motor						

## C - Abrasive environments (mechanical seal)

Some environments can be very harmful. The mirror seal gives reinforced motor sealing.

Mechanical seal

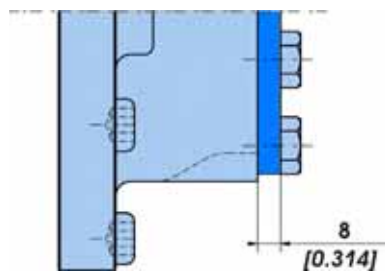


These seals are available for standard wheel motors and short wheel motors.

## E - Reinforced sealing

Requires reinforced seals and, for an unbraked motor, a rear reinforced plate (R25 - 15 [0.594] thick, instead of 6 [0.237]).

	C	D	F	P	S
	1	1 2 3	1 2 3	1 2 3 4	1 2 3 4 5 6
M S 2 5	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/> <input checked="" type="checkbox"/> <input checked="" type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>



## G - Special wheel rim mounting

Enables certain combinations different from the standard mountings defined on page 10.



Consult your Poclain Hydraulics sales engineer.

Modularity and  
Model code

Wheel motor

Shaft motor

Valving systems  
and hydrobases

Brake

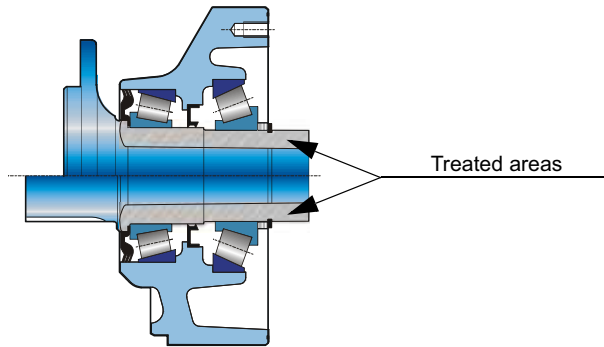
Options





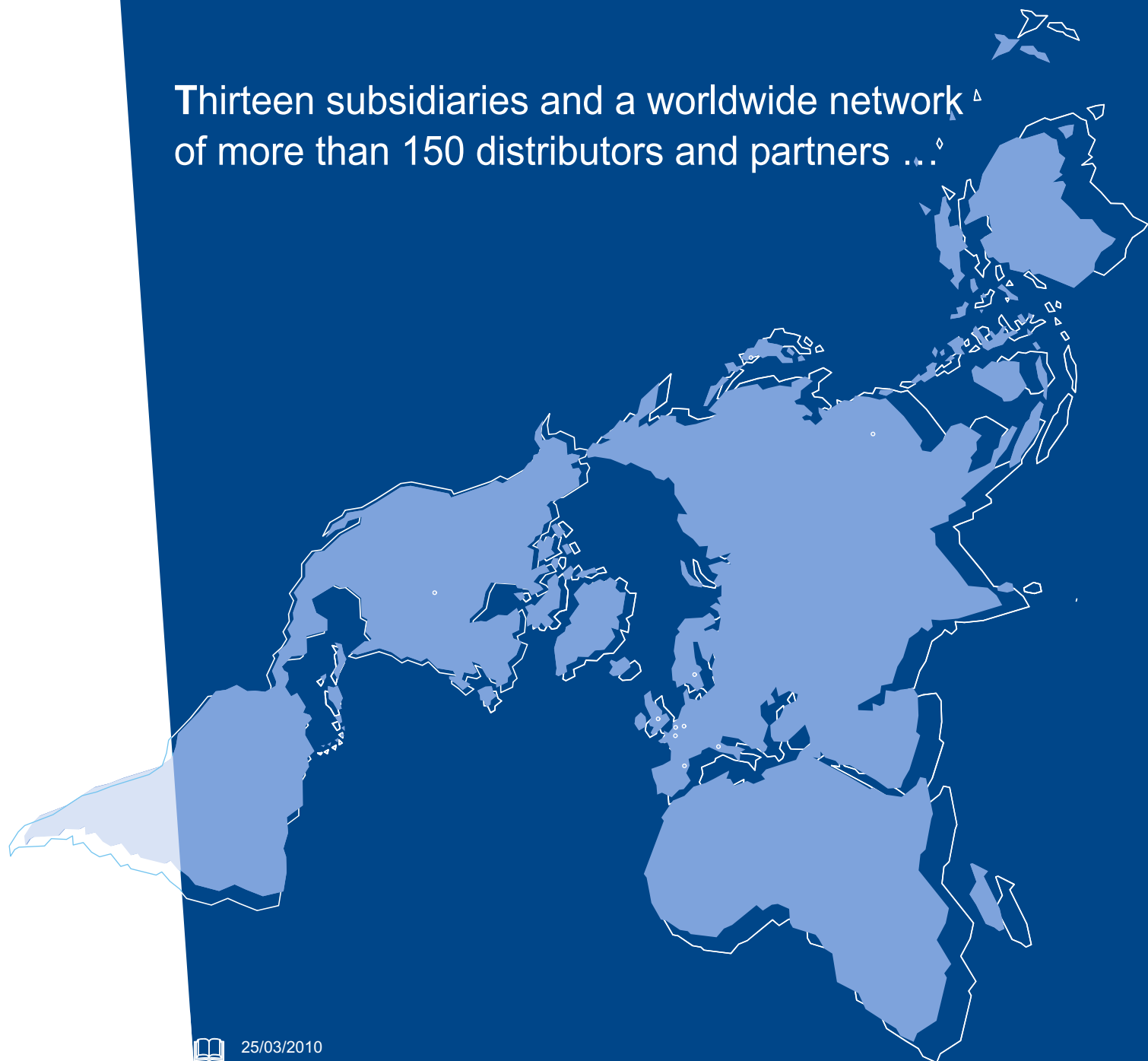
## J - Treated shaft

Heat treatment on the indicated bearing radius and splines.





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	801 478 192F
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	801 578 117U
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